# Section 3-02 Horizontal Alignment and Superelevation

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# HORIZONTAL ALIGNMENT

**General:** The operational characteristics of a roadway are directly affected by its alignment. The alignment, in turn, affects vehicle operating speeds, sight distances, and highway capacity. The horizontal alignment is influenced by many factors including:

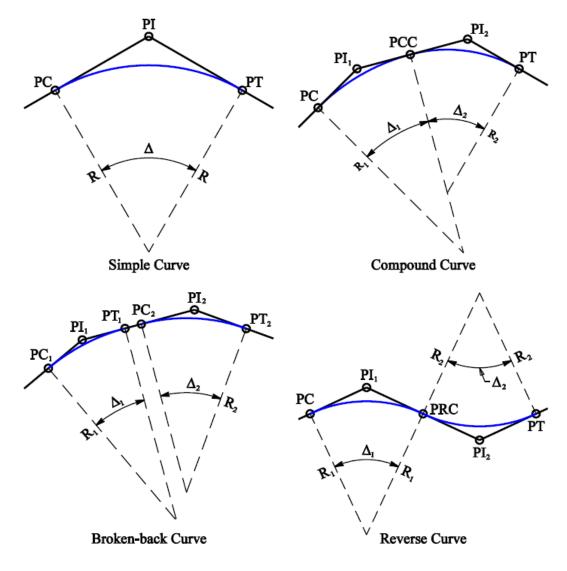
- Terrain
- Functional classification
- Design speed
- Traffic volume
- Right-of-way availability
- Environmental concerns
- Anticipated level of service

The horizontal alignment must provide a safe, functional roadway facility that provides adequate sight distances within economical constraints. The alignment must adhere to specific design criteria such as minimum radii, superelevation rates, and sight distance. These criteria will maximize the overall safety of the facility and enhance the aesthetic appearance of the highway.

Construction of roadways along new alignments is relatively rare. Typically, roadways are reconstructed along existing alignments with horizontal and/or vertical changes to meet current design criteria. The horizontal alignment of a roadway is defined in terms of straight-line tangents and horizontal curves. The curves allow for a smooth transition between the tangent sections. Circular curves and spiral curves are two types of horizontal curves utilized to meet the various design criteria.

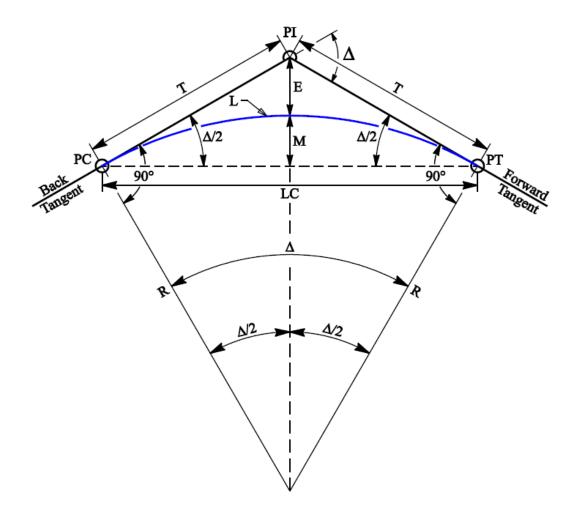
**Circular Curves:** The most common type of curve used in a horizontal alignment is a simple circular curve. A circular curve is an arc with a single constant radius connecting two tangents. A compound curve is composed of two or more adjoining circular arcs of different radii. The centers of the arcs of the compound curves are located on the same side of the alignment. The combination of a short length of tangent between two circular curves is referred to as a broken-back curve. A reverse curve consists of two adjoining circular arcs with the arc centers located on opposite sides of the alignment. Compound and reverse curves are generally used only in specific design situations such as mountainous terrain.

EXHIBIT 1 illustrates four examples of circular curves. The tangents intersect one another at the point of intersection (PI). The point at which the alignment changes from a tangent to circular section is the point of curvature (PC). The point at which the alignment changes from a circular to a tangent section is the point of tangency (PT). The point at which two adjoining circular curves turning in the same direction meet is the point of compound curvature (PCC). The point at which two adjoining circular curves turning in opposite directions meet is the point of reverse curvature (PRC).



# **EXHIBIT 1** CIRCULAR CURVES

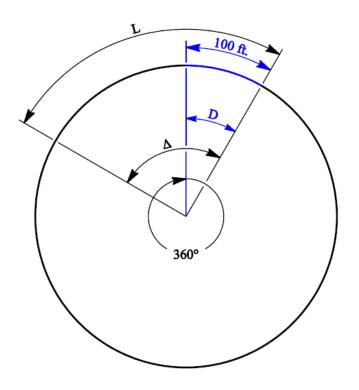
EXHIBIT 2 is an illustration of the standard components of a single circular curve connecting a back and forward tangent. The distance from the PC to the PI is defined by the tangent distance (T). The length of the circular curve (L) is dependent on the central angle ( $\Delta$ ) and the radius (R) of the curve. Since the curve is symmetrical about the PI, the distance from the PI to the PT is also defined by the tangent distance (T). A line connecting the PC and PT is the long chord (LC). The external distance (E) is the distance from the PI to the midpoint of the curve. The middle ordinate (M) is the distance from the midpoint of the curve to the midpoint of the long chord.



**EXHIBIT 2** CIRCULAR CURVE COMPONENTS

Using the arc definition for a circular curve, the degree of curvature is the central angle (D) subtended by a 100 ft arc. A circle has an internal angle of 360° and a circumference of  $2\pi R$ . Refer to EXHIBIT 3 for an illustration of the degree of curvature within a circle. The relationship between the central angle and the radius for a given circular curve is:

$$\frac{D}{360^{\circ}} = \frac{100 \ ft}{2\pi R}; \quad D = \frac{(100 \ ft)(360^{\circ})}{2\pi R} = \frac{5729.58 \ ft}{R}$$
$$\frac{\Delta}{360^{\circ}} = \frac{L}{2\pi R}; \quad \Delta = \frac{L * 360^{\circ}}{2\pi R} = \frac{L * 180^{\circ}}{\pi R}; \quad L = \frac{\Delta \pi R}{180^{\circ}}$$
$$\frac{D}{\Delta} = \frac{100}{L}; \quad L = \frac{100\Delta}{D}$$



**EXHIBIT 3** DEGREE OF CURVATURE

**General Circular Curve Formulas:** 

$$T = R \tan \frac{\Delta}{2}$$
$$L = \frac{100\Delta R}{5729.58} = \frac{100\Delta}{D}$$
$$LC = 2R \sin \frac{\Delta}{2}$$
$$E = \frac{R}{\cos \frac{\Delta}{2}} - R$$
$$M = E \cos \frac{\Delta}{2}$$

Stationing:

$$Sta. PC = Sta. PI - T$$

Sta.PT = Sta.PC + L

#### **Example Circular Curve Problem:**

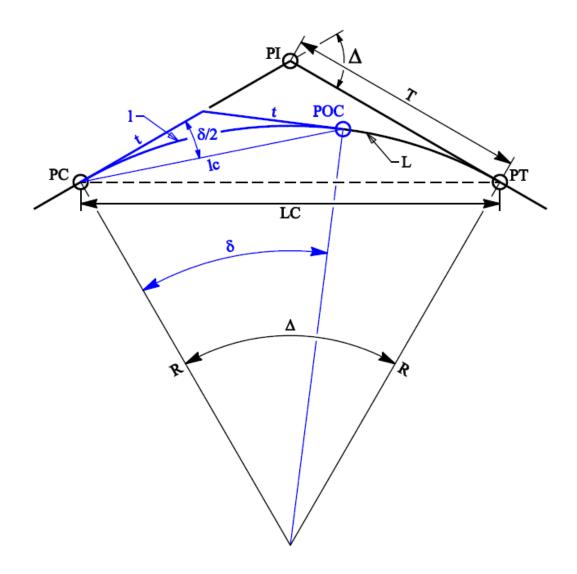
Given: Sta. PI = 100+00 Radius = 4200 ft  $\Delta = 27^{\circ}$ Find: Sta. PT Solution:  $T = R \tan \frac{\Delta}{2} = 4200 \tan \frac{27}{2} = 1008.33 ft$  Sta. PC = Sta. PI - T = 10000.00 - 1008.33 = 8991.67 or 89 + 91.67  $L = \frac{100\Delta R}{5729.58} = \frac{100 * 27 * 4200}{5729.58} = 1979.20 ft$  Sta. PT = Sta. PC + L = 8991.67 + 1979.20= 10970.87 or 109 + 70.87

#### Locating a point on a circular curve (see EXHIBIT 4):

The position of any point located at a distance l from the PC along a curve can be determined by utilizing the circular curve formulas.

$$t = R \tan \frac{\delta}{2}$$
$$D = \frac{5729.58}{R}$$
$$l = \frac{100\delta R}{5729.58} = \frac{100\delta}{D}$$
$$lc = 2R \sin \frac{\delta}{2}$$

Where *lc*,  $\tau$  and  $\delta$  mimic LC, T and  $\Delta$  of the whole curve elements.

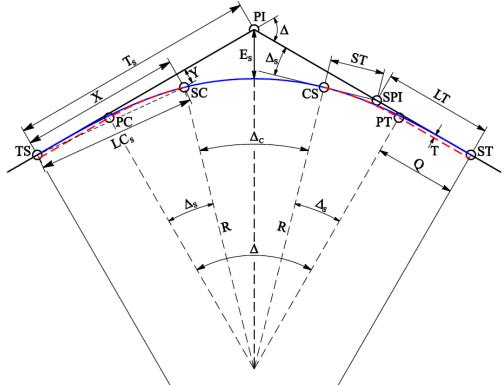


**EXHIBIT 4** POINT ON A CIRCULAR CURVE

**Spiral Curves:** Spiral curves are used in horizontal alignments to provide a gradual transition between tangent sections and circular curves. While a circular curve has a radius that is constant, a spiral curve has a radius that varies along its length. The radius decreases from infinity at the tangent to the radius of the circular curve it is intended to meet.

A vehicle entering a curve must transition from a straight line to a fixed radius. To accomplish this, the vehicle travels along a path with a continually changing radius. Consequently, a spiral will more closely duplicate the natural path of the turning vehicle. If the curvature of the alignment is not excessively sharp, the vehicle can usually traverse this spiral within the width of the travel lane. When the curvature is relatively sharp for a given design speed, it may become necessary to place a spiral transition at the beginning and end of the circular curve. The spirals allow the vehicle to more easily transition into and out of a curve while staying within the travel lane.

EXHIBIT 5 illustrates the standard components of a spiral curve connecting tangents with a central circular curve. The back and forward tangent sections intersect one another at the point of intersection (PI). The alignment changes from the back tangent to the entrance spiral at the tangent to spiral (TS) point. The entrance spiral meets the circular curve at the spiral to curve (SC) point. The circular curve meets the exit spiral at the curve to spiral (CS) point. The alignment changes from the exit spiral to the forward tangent at the spiral to tangent (ST) point. The entrance and exit spiral at each end of the circular curve are geometrically identical.



**EXHIBIT 5** SPIRAL CURVE COMPONENTS

The length of the circular curve ( $L_C$ ) is dependent on its central angle ( $\Delta_C$ ) and radius (R). The central angle ( $\Delta$ ) of the spiral-curve-spiral combination represents the deflection angle between the tangent sections. When spirals are placed at either end of the circular curve, the length of the curve is shortened. Instead of extending from the PC to the PT, the curve now extends from the SC to the CS. The offset distance or throw distance (T) represents the perpendicular distance from the back (or forward) tangent section to a tangent line extending from the PC (or PT) points. The length of the spiral ( $L_S$ ) is typically determined by design speed and superelevation rates. The total length (L) of the spiral-curve-spiral combination is the sum of the length of curve ( $L_C$ ) and the length of both spirals ( $L_S$ ).

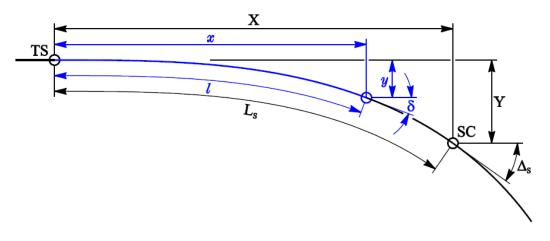
The distance from the TS to the PI is defined by the tangent distance  $(T_S)$ . The external distance  $(E_S)$  is the distance from the PI to the midpoint of the circular curve. A line connecting the TS and SC (or the CS to the ST) is the long chord  $(LC_S)$  of the spiral. The Q dimension is the perpendicular distance from the TS to the PC (and the PT to the ST). The X dimension represents the distance along the tangent from the TS to the SC (and the CS to the ST). The Y dimension represents the tangent offset at the SC (and the CS). The LT and ST dimensions represent the long tangent and the short tangent of the spiral. The spiral tangents intersect at the spiral point of intersection (SPI).

**General Spiral Equations:** The central angle of a spiral ( $\Delta$ s) is a function of the average degree of curvature of the spiral. In other words,  $\Delta$ s of a spiral is one half of the central angle ( $\Delta$ <sub>C</sub>) for a circular curve of the same length and degree of curvature. These measurements are dependent on the spiral length (L<sub>s</sub>) and central angle ( $\Delta$ <sub>s</sub>).

Since  $\Delta_c = DL_c/100$  then  $\Delta_s = DL_s/200$   $\Delta = \Delta_c + 2\Delta_s$   $L = L_c + 2L_s$   $T_s = (R + T) \tan{\frac{\Delta}{2}} + Q$  $E_s = \frac{(R + T)}{\cos{\frac{\Delta}{2}}} - R$ 

#### Locating a point on a spiral curve:

The position of any point located at a distance l from the TS along a spiral can be determined by modifying the spiral curve formulas.



**EXHIBIT 6** POINT ON A SPIRAL CURVE

The deflection angle ( $\delta$ ) at the intermediate point can be determined by the equation:

$$\delta = \Delta_S \frac{l^2}{{L_S}^2}$$

Using the equation for determining the spiral central angle equation,  $\delta$  can also be solved by:

$$\Delta_S = \frac{DL_S}{200}; \quad \delta = \frac{Dl^2}{200L_S}$$

By using differential geometry and an infinite series for the sine and cosine functions, the distance along the tangent (x) and the tangent offset (y) can be determined. In the following equations,  $\delta$  must be converted to radians by multiplying the angle in degrees by  $\pi/180$ .

$$x = l(1 - \frac{\delta^2}{(5)(2!)} + \frac{\delta^4}{(9)(4!)} - \frac{\delta^6}{(13)(6!)} + \cdots)$$
$$y = l(\frac{\delta}{3} - \frac{\delta^3}{(7)(3!)} + \frac{\delta^5}{(11)(5!)} - \frac{\delta^7}{(15)(7!)} + \cdots)$$

The X and Y values can be calculated by substituting  $L_S$  for l, and  $\Delta_S$  for  $\delta$ . After X and Y have been determined, the following values can be calculated using these equations:

$$Q = X - R \sin \Delta_S; \quad T = Y - R(1 - \cos \Delta_S)$$
$$ST = \frac{Y}{\sin \Delta_S}; \quad LT = X - ST \cos \Delta_S$$
$$LC_S = \sqrt{(X \cos \Delta_S + Y \sin \Delta_S)^2 + (X \sin \Delta_S - Y \cos \Delta_S)^2}$$

#### **Spiral Curve Stationing Calculations:**

$$Sta.TS = Sta.PI - T_S$$
  
 $Sta.SC = Sta.TS + L_S$   
 $Sta.CS = Sta.SC + L_C$   
 $Sta.ST = Sta.CS + L_S$ 

### **Spiral Curve Stationing Example:**

Given: Sta. PI = 100+00  

$$L_S = 150 \text{ ft}$$
  
 $\Delta = 35^{\circ}$   
 $D = 10^{\circ}$   
Find: Sta. TS, Sta. SC, Sta. CS,  
and Sta. ST

Solution:

$$R = \frac{5729.58}{D} = \frac{5729.58}{10} = 572.96 \, ft$$
$$\Delta_S = \frac{DL_S}{200} = \frac{10 * 150}{200} = 7.5^{\circ}$$
$$\Delta = \Delta_C + 2\Delta_S; \ \Delta_C = \Delta - 2\Delta_S = 35^{\circ} - 2 * 7.5^{\circ} = 20^{\circ}$$
$$L_C = \frac{100\Delta c}{D} = \frac{100 * 20}{10} = \frac{2000}{10} = 200.00 \, ft$$

Calculate the values for the spiral components T and Q, as described in the preceeding example. The calculated values will be: T = 1.64', Q = 74.96'.

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$$T_{S} = (R + T) \tan \frac{\Delta}{2} + Q = (572.96 + 1.64) \tan \frac{35}{2} + 74.96 = 256.13 \text{ ft}$$

$$Sta.TS = Sta.PI - T_{S} = 10000.00 - 256.13$$

$$= 9743.87 \text{ or } 97 + 43.87$$

$$Sta.SC = Sta.TS + L_{S} = 9843.87 + 150.00$$

$$= 9893.87 \text{ or } 98 + 93.87$$

$$Sta.CS = Sta.SC + L_{C} = 9893.87 + 200.00$$

$$= 10093.87 \text{ or } 100 + 93.87$$

$$Sta.ST = Sta.CS + L_{S} = 10093.87 + 150.0$$

$$= 10243.87 \text{ or } 102 + 43.87$$

Approximate Method of Calculating X and Y: The spiral deflection between the tangent section and the spiral long chord is approximately  $\frac{1}{3}$  of the spiral deflection angle ( $\Delta_s$ ). By using these substitutions, the calculations for the spiral components may be greatly simplified.

$$Y = L_S * \sin\frac{\Delta_S}{3}; \quad X^2 + Y^2 = {L_S}^2 \text{ or } X = \sqrt{{L_S}^2 - Y^2}$$
$$Q = \frac{X}{2}; \quad T = \frac{Y}{4}$$
$$ST = \sin\frac{\Delta_S}{3} * \frac{L_S}{\sin\Delta_S}; \quad LT = \sin\frac{2\Delta_S}{3} * \frac{L_S}{\sin\Delta_S}$$

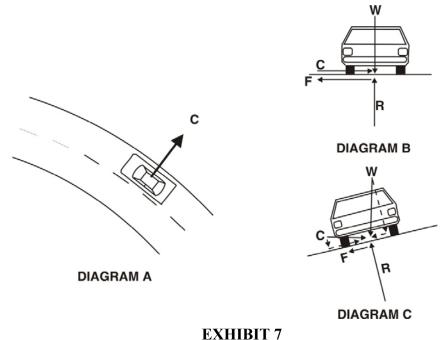
#### **SUPERELEVATION**

**General:** Centrifugal force is the outward pull on a vehicle traversing a horizontal curve. When traveling at low speeds or on curves with large radii, the effects of centrifugal force are minor. However, when traveling at higher speeds or around curves with smaller radii, the effects of centrifugal force increase. Excessive centrifugal force may cause considerable lateral movement of the turning vehicle and it may become impossible to stay inside the driving lane.

Superelevation and side friction are the two factors that help stabilize a turning vehicle. Superelevation is the banking of the roadway such that the outside edge of pavement is higher than the inside edge. The use of superelevation allows a vehicle to travel through a curve more safely and at a higher speed than would otherwise be possible. Side friction developed between the tires and the road

surface also acts to counterbalance the outward pull on the vehicle. Side friction is reduced when water, ice, or snow is present or when tires become excessively worn.

If the pavement cross-slope is flat, side friction between the tires and the pavement is the only force that keeps the vehicle traveling on the curved path. Banking the vehicle by adding superelevation has two effects. It reduces the component of centrifugal force acting parallel to the pavement surface, and more importantly, it generates a component of the weight of a vehicle acting in a direction parallel to the pavement to resist and thereby reduce the effect of centrifugal force. Superelevation reduces the amount of side friction required to hold a vehicle on a curved path (side friction always acts in a direction parallel to the pavement) and consequently reduces the sensation the driver feels of being pushed towards the outside of a curve.



VEHICLE ON CURVE FORCE DIAGRAMS

The concept is best illustrated when looking at a diagram of the forces acting on a vehicle traveling a curved alignment as shown in EXHIBIT 7. For this analysis, we are only interested in the forces parallel to the pavement. In Diagram B, no superelevation exists, hence the entire value of centrifugal force (C) acts parallel to the pavement. Side friction force (F) must be equal in magnitude to C and must work in the opposite direction of C, or the vehicle will skid.

In Diagram C, superelevation is applied, resulting in a somewhat smaller force component of C acting parallel to the pavement. Additionally, the force of gravity pulling down on the mass of the vehicle (W) now has a component that acts parallel to the pavement cross-slope, thereby resisting the parallel component of

centrifugal force. The magnitude of the side friction force becomes much smaller. If enough superelevation is added, no side friction component is required. If excessive superelevation is provided, the parallel weight component becomes greater than the parallel centrifugal force component, thereby requiring side friction in the opposite direction. This creates an unnatural driving maneuver since it requires the driver to steer back towards the outside of the curve; therefore, excessive superelevation should be avoided.

The transitional rate of applying superelevation into and out of curves is influenced by several factors. These factors include design speed, curve radius, and number of travel lanes. Minimum curve radii for a horizontal alignment are determined by the design speed and superelevation rate. Higher design speeds require more superelevation than lower design speeds for a given radius. Additionally, sharper curves require more superelevation than flatter curves for a given design speed.

The maximum superelevation for a section of roadway is dependent on climatic conditions, type of terrain, and type of development. Roadways in rural areas are typically designed with a maximum superelevation rate of 8 percent. In mountainous areas, a maximum superelevation rate of 6 percent is used due to the increased likelihood of ice and snow. Urban roadways are normally designed with a maximum superelevation rate of 4 percent. Superelevation is of limited use in urban areas because of the lower operating speeds. In most cases, superelevation in urban areas is completely eliminated. The superelevation of the roadway may interfere with drainage systems, utilities, and pavement tie-ins at intersecting streets and driveways.

**Maximum Allowable Side Friction Factor:** The maximum allowable side friction factor (f) is established for each design speed based on studies that have been conducted for a variety of tires, pavement types and conditions. The side friction factor is the side coefficient of friction which when multiplied by the weight of the vehicle, gives the resultant side friction force. Since highway curves are designed to avoid skidding with a sufficient margin of safety, the maximum allowable side friction factor is significantly below the side coefficient of friction for impending skid. In fact, a major consideration in selecting the maximum allowable side friction factors is the point at which the **sensation** of centrifugal force will cause the driver to experience enough discomfort to react instinctively to avoid greater lateral forces. The *ASHTO A Policy on Geometric Design of Highways and Streets* has established the maximum allowable side friction factors are shown in EXHIBIT 8.

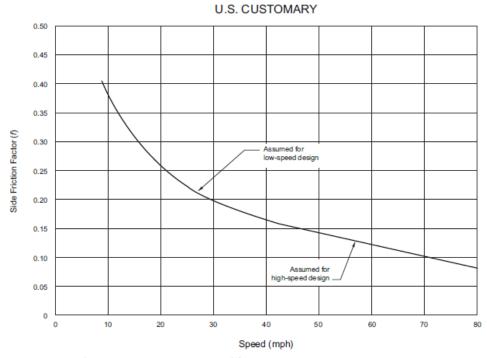


Figure 3-6. Side Friction Factors Assumed for Design



**Minimum Radius:** The simplified curve formula relates the balance of forces between the centrifugal force, the side friction force and the effect of superelevation. In its fundamental form the simplified curve formula is:

$$f = \frac{V^2}{15R} - 0.01e$$

where: f = side friction factor V = vehicle speed, mph R = radius of curve, ft e = superelevation rate, %

The minimum radius for a given design speed can be calculated by substituting e(max) for e, f(max) for f and the design speed for V into the simplified curve formula.

**Distribution of Superelevation for High Speed Roadways (>45 mph):** The simplified curve formula shown above establishes a linear relationship between the sum of superelevation (e) and friction factor (f) and the inverse of the radius,

for a given design speed. Although the relationship is linear for the sum of e and f, the simplified curve formula does not indicate how e and f are individually distributed. For high speed roadways, it is recognized that many drivers tend to overdrive the flat to intermediate range of curves (i.e. those curves which are flatter than the minimum radius curves for a given design speed). Rather than applying a straight line distribution of superelevation from 0 to e(max) as the inverse of the radius varies from 0 to 1/R(min), it becomes desirable to distribute e (and thereby f) parabolically so that less side friction is required in the flat to intermediate range of curves by providing additional superelevation. This procedure is described in the AASHTO Policy as Method 5.

Method 5 has an asymmetrical parabolic form and represents a practical distribution for superelevation over the range of curvature. Method 5 is recommended for the distribution of e and f for all curves with radii greater than the minimum radius of curvature on rural highways, urban freeways, and high-speed urban streets.

The WYDOT 0.08, 0.06, 0.04 maximum superelevation tables were calculated using the aforementioned methodology. The designer should choose the appropriate table based on the criteria below:

<u>CONDITION</u>	SUPERELEVATION TABLE
Rural Design - (except for mountainou	us) 0.08 max
Rural Design - mountainous terrain	0.06 max
Urban Design – high speed (>45 mph)	0.04 or 0.06 max
Urban Design – low speed (<45 mph)	0.04 max

Note: Use of 0.04 max superelevation tables should be limited to urban design.

The WYDOT Superelevation Tables are included at the end of this Chapter.

**Distribution of Superelevation for Low Speed Urban Roadways (<45 mph):** It is desirable to use the e(max) = 0.04 ft/ft superelevation tables for low speed urban roadways. In many cases the designer may wish to also limit the minimum radius to curves that require no more than 0.02 ft/ft of superelevation (i.e. reverse crown). Drainage and connections to intersecting roads can be more easily dealt with in an urban environment when superelevation is kept to a minimum. In most cases, superelevation in urban areas is completely eliminated. The superelevation of the roadway may interfere with drainage systems, utilities, and pavement tie-ins at intersecting streets and driveways.

If used, the designer may consider other methods of superelevation distribution for low speed (45 mph and less) urban design. As previously discussed, when the friction factor reaches its maximum allowable value, the driver feels the greatest level of discomfort due to centrifugal force. Method 2 from AASHTO Policy is acceptable for low speed urban streets where drivers have been conditioned to expect a greater level of discomfort. In this method, no superelevation is applied until the maximum allowable friction factor is required. Superelevation is then added as needed to counteract the centrifugal force while holding f at f(max). This discourages drivers from "overdriving" conditions (i.e. exceeding the design speed) because less superelevation is used to offset centrifugal force which now pulls harder on the driver and vehicle. The designer must weigh other conditions such as the roadway function, drainage, and good geometry at connecting roads and approaches in selecting appropriate superelevation rates. In all cases, the maximum allowable side friction factor should not be exceeded.

**Superelevation Runoff:** Superelevation runoff length (S) is defined as the distance to go from zero (e = 0.00) to the specified superelevation (e) for the given radius and design speed. Superelevation runoff length is calculated for a two lane roadway rotated about the centerline by applying the established maximum relative gradients and then adjusting the runoff length for wider roadways or roadways with a different point of rotation.

The maximum relative gradient is defined as the difference between the longitudinal slope between the centerline profile and the edgeline profile (edge of traveled way) for a two lane roadway rotated about the centerline. The maximum recommended relative gradients from AASHTO Policy are shown in Exhibit 9.

Design Speed (mph)	Maximum Relative Gradient (%)
15	0.78
20	0.74
25	0.70
30	0.66
35	0.62
40	0.58
45	0.54
50	0.50
55	0.47
60	0.45
65	0.43
70	0.40
75	0.38
80	0.35

### **EXHIBIT 9** MAXIMUM RELATIVE GRADIENTS

Superelevation runoff length can be calculated with the following formula:

$$L_r = \frac{(wn_1) e_d}{\Delta} (b_w)$$

where:

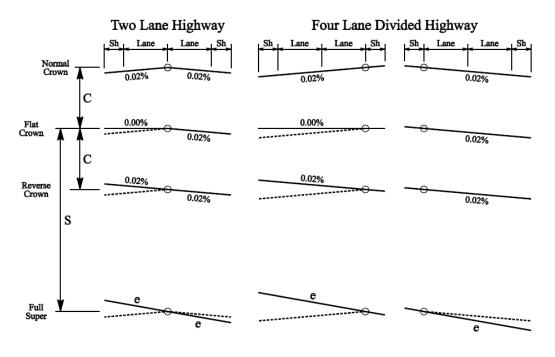
- $L_r$  = minimum length of superelevation runoff, ft
- w = width of one traffic lane, ft (typically 12 ft)
- $n_1$  = number of lanes rotated
- $e_d$  = design superelevation rate, percent
- $b_w$  = adjustment factor for number of lanes rotated
- $\Delta$  = maximum relative gradient, percent

Superelevation is gradually introduced by rotating the pavement cross-section about a point of rotation. For undivided highways, the point of rotation is located at the centerline. For divided highways, the point of rotation is typically located at the inside edge of traveled way. The location of the point of rotation is generally indicated on the roadway typical sections. Superelevation is applied by first rotating the lane(s) on the outside of the curve. The inside lane(s) do not rotate until the outside lane(s) achieve a reverse crown. At this point, all lanes rotate simultaneously until full superelevation is reached.

**Crown Runoff:** Crown runoff (C) is the distance required for the outside lane(s) to transition from a normal crown to a flat crown. The length of crown runoff is also the distance for the outside lane(s) to transition from a flat crown to a reverse crown. For each given superelevation and corresponding runoff length, the roadway cross-slope will rotate at a given rate. Crown runoff should occur at the same rate as superelevation runoff to create a smooth transition. The crown runoff length is, therefore, equal to the superelevation runoff length (S) multiplied by the ratio of the normal crown rate to the actual superelevation rate. Normal crown (NC) for most WYDOT projects is 0.020 ft/ft.

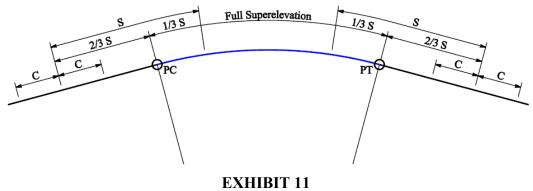
$$C = S * (NC/e)$$

The values of C and S are determined from superelevation tables for various combinations of design speed and degree of curvature.



**EXHIBIT 10** SUPERELEVATION ROTATION

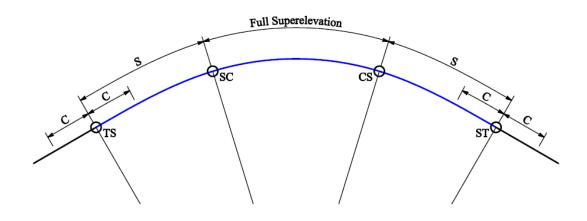
**Superelevation on Circular Curves:** Superelevation is uniformly applied to provide a smooth transition from a normal crown section to a full superelevation section. Two-thirds of superelevation runoff occurs prior to the PC and then again after the PT. One-third of the superelevation runoff occurs on the curve between the PC and the PT at each end of the curve. The rest of the curve is in a full superelevation section. The crown runoff that transitions from a normal crown to a flat crown (and vice versa) is placed outside each superelevation runoff section. The crown runoff that transitions from a flat crown to a reverse crown (and vice versa) is placed just inside each superelevation runoff section. See EXHIBIT 11 for an illustration of the crown and superelevation runoff distances as they are applied to circular curves.





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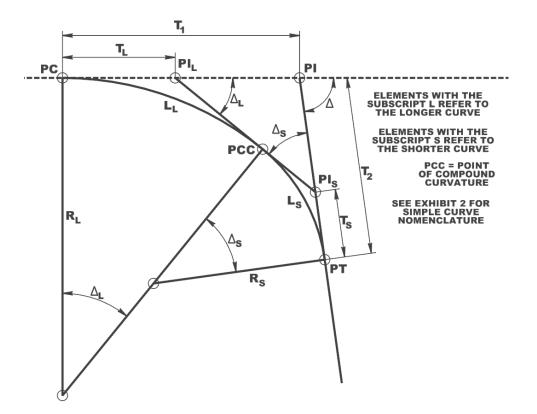
**Superelevation on Spiral Curves:** Where spiral transition curves are used, the full length of the spiral is equal to the superelevation runoff. The full superelevation is reached at the SC point and the entire circular curve is in a full superelevation section. The crown runoffs that transition from a normal crown to a flat crown (and vice versa) occurs prior to the TS point and after the ST point. The crown runoff that transitions from a flat crown to a reverse crown is placed just after the TS point and before the ST point. See EXHIBIT 12 for an illustration of the crown and superelevation runoff distances as they are applied to spiral curves.



**EXHIBIT 12** SUPERELEVATION ON A SPIRAL/CIRCULAR CURVE COMBINATION

**Compound and Reverse Curves:** Compound and reverse curves can sometimes be used advantageously in certain design situations. Because of their unique configuration, compound and reverse curves demand careful consideration when applying superelevation. The use of these alignments should be restricted to cases where non-consecutive curves with or without spirals are not effective and do not fit the terrain and proposed alignment. See EXHIBIT 13 for typical compound curves, and EXHIBIT 14 for reverse curves.

As a general rule, the ratio of the larger radius curve to the smaller radius curve should not be greater than 1.5 to 1 for open highways. The ratio for slower speed highways should not exceed 2 to 1. Superelevation runoff needs to be carefully considered for compound and reverse curves.



#### **EXHIBIT 13** COMPOUND CURVES

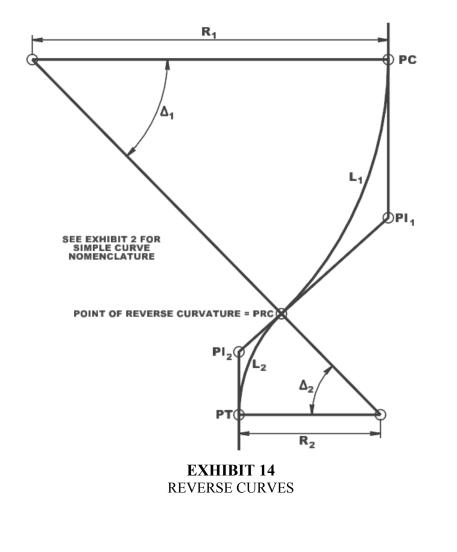
**Compound Curvature Design Considerations:** Superelevation and crown runoff areas demand careful consideration for consecutive curves in the same or opposite directions. WYDOT considers the desirable length of normal crown tangent to be a minimum of 200 feet between consecutive curve sections as shown in EXHIBIT 15.

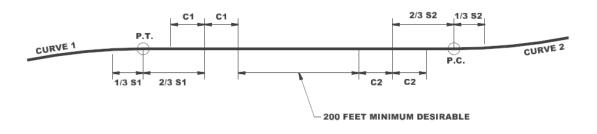
If there is not room for 200 feet of normal crown tangent or if the total tangent length between curves is less than two-thirds S1 + two-thirds S2 (see diagram), the designer will want to consider alternate means of providing superelevation runoff distance.

Although there are several ways to design these areas, there is no one best approach. The designer will need to decide which method or combination of methods is appropriate for the given situation.

Two-thirds of superelevation runoff is typically off the curve while one-third is typically on the curve. Consideration could be given to running off up to one-half of the superelevation on the curve to avoid overlapping adjacent runoff lengths.

The designer could also utilize a tangent section with 0.01 ft/ft crown between curves to reduce the crown runoff length in tight situations.





**EXHIBIT 15** MINIMUM NORMAL CROWN DISTANCE

If consecutive curves are curving the same direction, (their centers are on the same side) then consider holding 0.02 ft/ft reverse crown between the superelevation runoff areas instead of attempting to rotate to normal crown.

The designer can have the superelevation of the first curve transition directly into the superelevation rate of the second consecutive curve, taking care to avoid drainage problems on long flat curves and also on the high/low point on vertical curves.

**Overall Horizontal Design Considerations:** Roadways should be designed to blend with the contours of the natural surroundings. The roadway should not appear awkward or unnatural by having a horizontal alignment that is inconsistent with the existing terrain. The roadway construction, when completed, should have minimal impact on the surroundings. The terrain in the vicinity of the new construction should blend into the natural condition as much as possible.

The design speed used for a particular section of roadway should be as high as practical, considering the nature of the surrounding terrain and the function of the roadway. Smooth transitions should be provided in areas where the design speed changes to allow the driver to gradually become accustomed to the changed condition.

Directional changes in alignment are best accomplished by using simple, circular curves, unless the use of spirals is recommended. Use of gradual curves with flatter superelevation is preferable where the terrain allows for it. Spirals increase safety and comfort on sharper curves, especially at higher design speeds. The use of sharp curvature, compound, or reverse curvature should only be used in critical areas such as mountainous terrain.

Rural curves that are gradual enough to not require superelevation will function better if reverse 0.02 ft/ft crown is applied. Otherwise, the driver on the side of the adverse crown experiences the discomfort caused by centrifugal force.

Superelevation is of limited use in urban areas because of the lower operating speeds. In most cases, superelevation in urban areas is completely eliminated. The superelevation of the roadway may interfere with drainage systems, utilities, and pavement tie-ins at intersecting streets and driveways.

			W	YDC	)T S	upei	relev	ation Tal	oles				
R	UF	RAI	_ C	)ES	SIC	SN	<b>e(</b>	max) :	= 0.08 ft/ft				
		L	ane	Adj	ustr	nent	t Fac	ctor L(adj	) = 1.0				
0.	ax)= 08 dj) =		e(max) f(max) GRAD	0.08 0.32 0.78		e(max) f(max) GRAD	0.08 0.27 0.74	L(adj) = 1.	Rev. 12-20-13 0 e roadways rotated about the				
1. 12 ft l	.0 Lanes		V(R) V(D)	15 15		V(R) V(D)	20 20	centerline.					
CU	RVE	15 m	iph (2	4km/h)	20 n	n <mark>ph</mark> (3	2km/h)	Definitions for Superelevation Tables					
R (ft)	D (deg)	e (ft/ft)	S (ft)	C (ft)	e (ft/ft)	S (ft)	C (ft)	R = Radius of Cur D = Degree of Cur	ve rve (100 ft arc length definition)				
23000	0.25	NC	0	0	NC	0	0	e = Superelevation	n Rate				
20000	0.29	NC	0	0	NC	0	0	S = Length of Sup	erelevation Runoff & Spiral Length				
17000	0.34	NC	0	0	NC	0	0		to full superelevation length.				
14000	0.41	NC	0	0	NC	0	0	WYDOT us	es 2/3 S off curve, 1/3 S on curve.				
12000	0.48	NC	0	0	NC	0	0	C = Length of Cro	wn Runoff				
10000	0.57	NC	0	0	NC	0	0	NC (normal	l crown) to flat crown length.				
8000	0.72	NC	0	0	NC	0	0	1	vn (typically 0.02 ft/ft)				
6000	0.95	NC	0	0	NC	0	0	RC = Reverse Cro	own (typically 0.02 ft/ft)				
5000	1.15	NC	0	0	NC	0	0						
4000	1.43	NC	0	0	NC	0	0	L(adj) = Lane Adji					
3500	1.64	NC	0	0	NC	0	0	1	just the length of S and C for				
3000	1.91	NC	0	0	NC	0	0	multilane hi	ghways.				
2500	2.29	NC	0	0	NC	0	0						
2000	2.86	NC	0	0	NC	0	0	L(adj) = 1.25	For 3 - lane roadways rotated				
1800	3.18	NC	0	0	NC	0	0		about the centerline.				
1600	3.58	NC	0	0	NC	0	0						
1400	4.09	NC	0	0	RC	32	32	L(adj) = 1.5	For 4 - lane roadways rotated				
1200	4.77	NC	0	0	RC	32	32		about the centerline, and divided				
1000	5.73	NC	0	0	0.023	37	32		4 - lane roadways rotated about				
900	6.37	NC	0	0	0.025	41	33		the median edge of traveled way.				
800	7.16	RC	31	31	0.028	45	32						
700	8.19	RC	31	31	0.031	50	32	L(adj) = 1.75	For 5 - lane roadways rotated				
600	9.55	0.022	34	31	0.035	57	33		about the centerline.				
500	11.46	0.026	40	31	0.040	65	33						
450	12.73	0.028	43	31	0.042	68	32	· ·	should be considered when				
400	14.32	0.031	48	31	0.045	73	32	e, S, and C are	snaueu.				
350	16.37	0.034	52	31	0.048	78	33	Superalsusties	luce based on AACUTO 2014				
300	19.10	0.038	58	31	0.051	83	33	-	lues based on AASHTO 2011				
250	22.92	0.043	66	31	0.055	89	32	Greenbook.					
200	28.65	0.048	74	31	0.060	97	32						
150	38.20	0.053	82	31	0.067	109	33						
100	57.30	0.061	94	31	0.077	125	32						
75	76.39	0.068	105	31	0.080	130	33						
50	114.59	0.077	118 118	31 28 <del>0</del>	D/-	nin) - 7	76.8						
		K(n	nin) = 3	00 11	L к(r	nin) = 7	σπ						

	WYDOT Superelevation Tables												
DI	JR/	<b>A I</b>	וח	=0			\/m	121	<u>ہ</u>	- 0	09	e ff	/ft
	ערול			_0			-(II	14/	<u> </u>	- 0	.00	, 10	/1L
		La	ne A	\dju	stme	ent F	act	or L(	adj)	= 1.	.0		
	ax)=		e(max)	0.08		e(max)	0.08		e(max)	0.08		e(max)	0.08
11	08 dj) =		f(max) GRAD	0.23 0.7		f(max) GRAD	0.20 0.66		f(max) GRAD	0.18 0.62		f(max) GRAD	0.16 0.58
	.0 .0		URAD	24		URAD	28		U(R)	32		URAD	36
	Lanes		V(D)	25		V(D)	30		V(D)	35	V(D) 40		
CU	RVE	25 mph (40km/h)			30 mph (48km/h)			35 mph (56km/h)			40 mph (64km/h)		
R	D	e	S	С	е	S	С	e	S	С	e	S	С
(ft)	(deg)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)
23000	0.25	NC	0	0	NC	0	0	NC	0	0	NC	0	0
20000	0.29	NC	0	0	NC	0	0	NC	0	0	NC	0	0
17000	0.34	NC	0	0	NC	0	0	NC	0	0	NC	0	0
14000	0.41	NC	0	0	NC	0	0	NC	0	0	NC	0	0
12000	0.48	NC	0	0	NC	0	0	NC	0	0	NC	0	0
10000	0.57	NC	0	0	NC	0	0	NC	0	0	NC	0	0
8000	0.72	NC	0	0	NC	0	0	NC	0	0	NC	0	0
6000	0.95	NC	0	0	NC	0	0	NC	0	0	NC	0	0
5000	1.15	NC	0	0	NC	0	0	NC	0	0	RC	41	41
4000	1.43	NC	0	0	NC	0	0	RC	39	39	RC	41	41
3500	1.64	NC	0	0	NC	0	0	RC	39	39	0.022	46	42
3000	1.91	NC	0	0	RC	36	36	0.021	41	39	0.026	54	42
2500	2.29	NC	0	0	RC	36	36	0.024	46	38	0.030	62	41
2000	2.86	RC	34	34	0.023	42	37	0.030	58	39	0.036	74	41
1800	3.18	RC	34	34	0.025	45	36	0.032	62	39	0.039	81	42
1600	3.58	0.021	36	34	0.028	51	36	0.035	68	39	0.043	89	41
1400	4.09	0.024	41	34	0.031	56	36	0.039	75	38	0.048	99	41
1200	4.77	0.027	46	34	0.036	65	36	0.044	85	39	0.053	110	42
1000	5.73	0.032	55	34	0.041	75	37	0.050	97	39	0.059	122	41
900	6.37	0.034	58	34	0.044	80	36	0.053	103	39	0.063	130	41
800	7.16	0.038	65	34	0.047	85	36	0.057	110	39	0.067	139	41
700	8.19	0.041	70	34	0.051	93	36	0.061	118	39	0.071	147	41
600	9.55	0.045	77	34	0.055	100	36	0.066	128	39	0.075	155	41
500	11.46	0.050	86	34	0.060	109	36	0.071	137	39	0.079	163	41
450	12.73	0.053	91	34	0.064	116	36	0.074	143	39			
400	14.32	0.055	94	34	0.067	122	36	0.077	149	39			
350	16.37	0.059	101	34	0.071	129	36 36	0.079	153	39			
300 250	19.10 22.92	0.063	108	34 34	0.075	136	36						
200	28.65	0.000	127	34	0.019	144	- 30						
150	38.20	0.079	135	34									
100	57.30	0.010											
75	76.39												
50	114.59												
		R(m	in) = 1:	34 ft	R(m	in) = 2	14 ft	R(m	in) = 3 <sup>-</sup>	14 ft	R(m	in) = 44	44 ft

			WY	DOT	' Sup	oere	leva	tion	Tab	les			
RI	JR/	Δ1	וח	FS	IGI	Ne	n)د	າລາ	d) =	= 0	08	R ft	/ft
									-			<u> </u>	
		La		-	stme								
	ax)= 08		e(max)	0.08 0.15		e(max)	0.08 0.14		e(max)	0.08 0.13		e(max)	0.08 0.12
	dj) =		f(max) GRAD	0.15		f(max) GRAD	0.14		f(max) GRAD	0.13		f(max) GRAD	0.12
	.0		V(R)	40		V(R)	44		V(R)	48	V(R)		52
	Lanes		V(D)	45		V(D)	50		V(D)	55		V(D)	60
	RVE	45 m		2km/h)	50 m	0 mph (80km/h)		55 mph (89km/h)		9km/h)			7km/h)
R	D	е	S	С	е	S	С	е	S	С	e	S	С
(ft)	(deg)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)
23000	0.25	NC	0	0	NC	0	0	NC	0	0	NC	0	0
20000	0.29	NC	0	0	NC	0	0	NC	0	0	NC	0	0
17000	0.34	NC	0	0	NC	0	0	NC	0	0	NC	0	0
14000	0.41	NC	0	0	NC	0	0	NC	0	0	NC	0	0
12000	0.48	NC	0	0	NC	0	0	NC	0	0	NC	0	0
10000	0.57	NC	0	0	NC	0	0	NC	0	0	RC	53	53
8000	0.72	NC	0	0	NC	0	0	RC	51	51	0.021	56	53
6000	0.95	RC	44	44	RC	48	48	0.024	61	51	0.027	72	53
5000	1.15	RC	44	44	0.024	58	48	0.028	71	51	0.032	85	53
4000	1.43	0.024	53	44	0.029	70	48	0.034	87	51	0.039	104	53
3500	1.64	0.027	60	44	0.032	77	48	0.038	97	51	0.044	117	53
3000	1.91	0.031	69	45	0.037	89	48	0.043	110	51	0.050	133	53
2500	2.29	0.036	80	44	0.043	103	48	0.050	128	51	0.057	152	53
2000	2.86	0.043	96	45	0.051	122	48	0.058	148	51	0.066	176	53
1800	3.18	0.047	104	44	0.055	132	48	0.063	161	51	0.070	187	53
1600	3.58	0.051	113	44	0.059	142	48	0.067	171	51	0.075	200	53
1400	4.09	0.056	124 136	44 45	0.064	154 168	48 48	0.072	184	51 51	0.078	208	53 53
1200	4.77				i			0.077	197		0.000	213	55
1000 900	5.73 6.37	0.068	151 158	44 45	0.076	182 187	48 48	0.080	204	51			
800	7.16	0.075	167	45	0.078	192	48						
700	8.19	0.078	173	44	0.000	132	40						
600	9.55	0.080	178	45									
500	11.46												
450	12.73												
400	14.32												
350	16.37												
300	19.10												
250	22.92												
200	28.65												
150	38.20												
100	57.30												
75	76.39												
50	114.59												
		R(m	iin) = 5	87 ft	R(m	in) = 7	58 ft	R(m	in) = 9	60 ft	R(mi	n) = 12	00 ft

			WY	рот	' Sup	oere	leva	tion	Tab	les			
RI	JR/	AL			_						30.	8 ft	/ft
					stme				-				
	iax)=		e(max)	0.08		e(max)	0.08		e(max)	0.08		e(max)	0.08
11	.08		f(max)	0.11		f(max)	0.10		f(max)	0.09		f(max)	0.08
	dj) = .0		GRAD	0.43		GRAD	0.4		GRAD	0.38		GRAD	0.35
	Lanes	V(R) 55				V(R) V(D)	58 70		V(R) V(D)	61 75		V(R) V(D)	64 80
	RVE	V(D) 65 65 mph (105km/h)			70 mph (113km/h			75 n	nph (12			nph (12	
R	D	e	S	C	e S C			e	S	C	e	C	
(ft)	(deg)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	(ft/ft)	S (ft)	(ft)
23000	0.25	NC	0	0	NC	0	0	NC	0	0	NC	0	0
20000	0.29	NC	0	0	NC	0	0	NC	0	0	NC	0	0
17000	0.34	NC	0	0	NC	0	0	NC	0	0	RC	69	69
14000	0.41	NC	0	0	NC	0	0	RC	63	63	RC	69	69
12000	0.48	RC	56	56	RC	60	60	RC	63	63	0.022	75	68
10000	0.57	RC	56	56	0.021	63	60	0.024	76	63	0.026	89	68
8000	0.72	0.024	67	56	0.026	78	60	0.029	92	63	0.033	113	68
6000	0.95	0.031	87	56	0.034	102	60	0.038	120	63	0.043	147	68
5000	1.15	0.036	100	56	0.040	120	60	0.045	142	63	0.051	175	69
4000	1.43	0.044	123	56	0.049	147	60	0.055	174	63	0.062	213	69
3500	1.64	0.049	137	56	0.055	165	60	0.062	196	63	0.070	240	69
3000	1.91	0.055	153	56	0.062	186	60	0.070	221	63	0.078	267	68
2500	2.29	0.064	179	56	0.071	213	60	0.078	246	63			
2000	2.86	0.073	204	56	0.079	237	60						
1800	3.18	0.077	215	56									
1600	3.58	0.079	220	56									
1400	4.09												
1200	4.77												
900	5.73 6.37												
700	7.16 8.19												
600	9.55												
500	11.46												
450	12.73												
400	14.32												
350	16.37												
300	19.10												
250	22.92												
200	28.65												
150	38.20												
100	57.30												
75	76.39												
50	114.59												
		R(mi	in) = 14	80 ft	R(mi	in) = 18	10 ft	R(mi	in) = 22	10 ft	R(mi	n) = 26	70 ft

	WYDOT Superelevation Tables													
	MT	'N.	D	ES	IG	Ne	e(n	1ax) =	0.06 ft/ft					
		L	ane	Adj	ustr	nen	t Fac	ctor L(adj	) = 1.0					
0.	ax)= 06 dj) =		e(max) f(max) GRAD	0.06 0.32 0.78		e(max) f(max) GRAD	0.06 0.27 0.74	L(adj) = 1. For 2 - Ian	Rev. 12-20-13 0 e roadways rotated about the					
	.0		V(R)	15		V(R)	20	centerline	e.					
	Lanes RVE		V(D) 1 <b>ph</b> (2	15 4km/h)	20 n	V(D) nph (3	20 32km/h)							
R	D	е	S	С	е	S	С							
(ft)	(deg)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	D = Degree of Cu	rve (100 ft arc length definition)					
23000	0.25	NC	0	0	NC	0	0	e = Superelevatio						
20000	0.29	NC	0	0	NC	0	0		perelevation Runoff & Spiral Length					
17000	0.34	NC NC	0	0	NC NC	0	0		to full superelevation length. ses 2/3 S off curve, 1/3 S on curve.					
12000	0.41	NC	0	0	NC	0	0	C = Length of Cro						
10000	0.57	NC	0	0	NC	0	0	-	I crown) to flat crown length.					
8000	0.72	NC	0	0	NC	0	0	-	vn (typically 0.02 ft/ft)					
6000	0.95	NC	0	0	NC	0	0		own (typically 0.02 ft/ft)					
5000	1.15	NC	0	0	NC	0	0							
4000	1.43	NC	0	0	NC	0	0	L(adj) = Lane Adj	ustment Factor					
3500	1.64	NC	0	0	NC	0	0	Used to ad	just the length of S and C for					
3000	1.91	NC	0	0	NC	0	0	multilane hi	ighways.					
2500	2.29	NC	0	0	NC	0	0							
2000	2.86	NC	0	0	NC	0	0	L(adj) = 1.25	For 3 - lane roadways rotated					
1800	3.18	NC	0	0	NC	0	0		about the centerline.					
1600	3.58	NC	0	0	NC	0	0		For the second second second second					
1400 1200	4.09 4.77	NC NC	0	0	RC RC	32 32	32 32	L(adj) = 1.5	For 4 - lane roadways rotated about the centerline, and divided					
1200	5.73	NC	0	0	0.022	36	33		4 - lane roadways rotated about					
900	6.37	NC	0	0	0.022	39	33		the median edge of traveled way.					
800	7.16	RC	31	31	0.026	42	32							
700	8.19	RC	31	31	0.028	45	32	L(adj) = 1.75	For 5 - lane roadways rotated					
600	9.55	RC	31	31	0.031	50	32		about the centerline.					
500	11.46	0.023	35	30	0.034	55	32							
450	12.73	0.025	38	30	0.035	57	33	Spiral transitions	should be considered when					
400	14.32	0.027	42	31	0.037	60	32	e, S, and C are	shaded.					
350	16.37	0.030	46	31	0.038	62	33							
300	19.10	0.032	49	31	0.041	66	32	-	alues based on AASHTO 2011					
250	22.92	0.034	52	31	0.043	70	33	Greenbook.						
200	28.65	0.037	57	31	0.047	76	32							
150 100	38.20 57.30	0.040	62 71	31 31	0.052	84 96	32 33							
75	76.39	0.046	80	31	0.005	- 50	- 33							
50	114.59	0.052	89	31										
			nin) = 3		R(n	nin) = {	31 ft							

	WYDOT Superelevation Tables													
N		1. C	DE	SI	GN	e(	m	ax)	) =	0.0	06	<b>ft</b> /1	ft	
					stme									
0. L(ad	ax)= 06 dj) = .0 Lanes		e(max) f(max) GRAD V(R) V(D)	0.06 0.23 0.7 24 25		e(max) f(max) GRAD V(R) V(D)	0.06 0.20 0.66 28 30		e(max) f(max) GRAD V(R) V(D)	0.06 0.18 0.62 32 35		e(max) f(max) GRAD V(R) V(D)	0.06 0.16 0.58 36 40	
	RVE	25 m		0km/h)	30 m	~ /	8km/h)	35 mph (56km/h)			40 mph (64km/h)			
R	D		e S C			s	C C	 e	s	C C	e 40 11	C		
(ft)	(deg)	(ft/ft)	(ft)	(ft)	e (ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	(ft/ft)	S (ft)	(ft)	
23000	0.25	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
20000	0.29	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
17000	0.34	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
14000	0.41	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
12000	0.48	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
10000	0.57	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
8000	0.72	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
6000	0.95	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
5000	1.15	NC	0	0	NC	0	0	NC	0	0	RC	41	41	
4000	1.43	NC	0	0	NC	0	0	NC	0	0	RC	41	41	
3500	1.64	NC	0	0	NC	0	0	RC	39	39	0.021	43	41	
3000	1.91	NC	0	0	RC	36	36	RC	39	39	0.024	50	42	
2500	2.29	NC	0	0	RC	36	36	0.023	45	39	0.028	58	41	
2000	2.86	RC	34	34	0.022	40	36	0.027	52	39	0.033	68	41	
1800	3.18	RC	34	34	0.024	44	37	0.029	56	39	0.035	72	41	
1600	3.58	RC	34	34	0.026	47	36	0.032	62	39	0.038	79	42	
1400	4.09	0.023	39	34	0.029	53	37	0.035	68	39	0.041	85	41	
1200	4.77	0.025	43	34	0.032	58	36	0.038	74	39	0.044	91	41	
1000	5.73	0.029	50	34	0.036	65	36	0.041	79	39	0.048	99	41	
900	6.37	0.031	53	34	0.037	67	36	0.043	83	39	0.050	103	41	
800	7.16	0.033	57	35	0.039	71	36	0.046	89	39	0.053	110	42	
700	8.19	0.035	60	34	0.042	76	36	0.049	95	39	0.056	116	41	
600	9.55	0.038	65	34	0.045	82	36	0.052	101	39	0.058	120	41	
500	11.46	0.040	69	35	0.048	87	36	0.056	108	39	0.060	124	41	
450	12.73	0.042	72	34	0.050	91	36	0.057	110	39				
400	14.32	0.044	75	34	0.053	96	36	0.059	114	39				
350	16.37	0.047	81	34	0.055	100	36	0.060	116	39				
300	19.10	0.050	86	34	0.058	105	36							
250	22.92	0.053	91	34	0.060	109	36							
200	28.65	0.057	98	34										
150	38.20	0.060	103	34										
100	57.30													
75	76.39													
50	114.59													
		R(mi	in) = 14	44 ft	R(m	in) = 2	31 ft	R(m	in) = 34	40 ft	R(m	in) = 48	85 ft	

			WY	DOT	Sup	oere	leva	tion	Tab	les				
N	ITN	1. C	DE	SIC	GN	e(	m	ax)	=	0.0	06	ft/1	ft	
					stme									
	ax)=		e(max)	0.06		e(max)	0.06	<b>`</b>	e(max)	0.06		e(max)	0.06	
	06 dj) =		f(max) GRAD	0.15 0.54		f(max) GRAD	0.14 0.5		f(max) GRAD	0.13 0.47	f(max) GRAD		0.12 0.45	
	.0		V(R)	40		V(R)	44		V(R)	48	V(R)		52	
12 ft I	Lanes		V(D) 45			V(D) 50			V(D) 55			V(D)		
CU	RVE	45 m	iph (7	2km/h)	50 m	nph (8	0km/h)	55 m	iph (8	9km/h)	60 m	1 <b>ph</b> (9	7km/h)	
R	D	е	S	С	е	S	С	е	S	С	е	S	С	
(ft)	(deg)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	
23000	0.25	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
20000	0.29	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
17000	0.34	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
14000	0.41	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
12000	0.48	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
10000	0.57	NC	0	0	NC	0	0	NC	0	0	RC	53	53	
8000	0.72	NC	0	0	NC	0	0	RC	51	51	RC	53	53	
6000	0.95	RC	44	44	RC	48	48	0.022	56	51	0.026	69	53	
5000	1.15	RC	44	44	0.022	53	48	0.026	66	51	0.030	80	53	
4000	1.43	0.023	51	44	0.027	65	48	0.031	79	51	0.036	96	53	
3500	1.64	0.026	58	45	0.030	72	48	0.034	87	51	0.039	104	53	
3000	1.91	0.029	64	44	0.034	82	48	0.038	97	51	0.043	115	53	
2500	2.29	0.033	73	44	0.038	91	48	0.043	110	51	0.048	128	53	
2000	2.86	0.038	84	44	0.043	103	48	0.049	125	51	0.054	144	53	
1800 1600	3.18 3.58	0.041	91 96	44 45	0.046	110 118	48 48	0.051	130 138	51 51	0.056	149 155	53 53	
1400	4.09	0.045	102	45	0.049	125	40	0.054	146	51	0.058		53	
1200	4.09	0.040	111	44	0.052	125	40	0.057	140	51	0.000	160	55	
1000	5.73	0.054	120	44	0.059	142	48	0.000	191	- 10				
900	6.37	0.054	120	44	0.059	144	40							
800	7.16	0.058	129	44										
700	8.19	0.060	133	44										
600	9.55													
500	11.46													
450	12.73													
400	14.32													
350	16.37													
300	19.10													
250	22.92													
200	28.65													
150	38.20													
100	57.30													
75	76.39													
50	114.59													
		R(m	in) = 6	43 ft	R(m	in) = 8	33 ft	R(min) = 1060 ft R(min) = 1330 ft						

	WYDOT Superelevation Tables													
MTN	1. D	ESI	GN	e(	m	ax)	=	0.0	06	ft/1	ft			
	Lane	e Adju	stme	ent F	act	or L(	(adj)	= 1.	.0					
e(max)=	e(m			e(max)	0.06		e(max)	0.06		e(max)	0.06			
0.06	f(m	1 C C		f(max)	0.10		f(max)	0.09		f(max) GRAD	0.08			
L(adj) = 1.0	GR/ V(R			GRAD V(R)	0.4 58		GRAD V(R)	0.38 61	V(R)		0.35 64			
12 ft Lanes	V(D	/		V(D)	70		V(D)	75		V(D)	80			
CURVE		(105km/h)	70 n	1 <b>ph</b> (11	3km/h)	75 m	1 <b>ph</b> (12	1km/h)	80 m	129 (129	9km/h)			
R D	e s		е	S	С	е	S	С	e	S	С			
(ft) (deg)	(ft/ft) (f	t) (ft)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)			
23000 0.25	NC (	0 (	NC	0	0	NC	0	0	NC	0	0			
20000 0.29		0 0	NC	0	0	NC	0	0	NC	0	0			
17000 0.34		0	NC	0	0	NC	0	0	NC	0	0			
14000 0.41		0 0	NC	0	0	RC	63	63	RC	69	69			
12000 0.48		6 56 6 56	RC 0.021	60 63	60 60	RC 0.023	63 73	63 63	0.021	72 86	69 69			
10000 0.57 8000 0.72		6 56 4 56	0.021	75	60	0.023	73 88	63	0.025	106	68			
6000 0.95	0.023 0		0.025	96	60	0.028	114	63	0.031	137	69			
5000 1.15		5 56	0.037	111	60	0.042	133	63	0.046	158	69			
4000 1.43	<u> </u>	12 56	0.044	132	60	0.049	155	63	0.055	189	69			
3500 1.64	0.044 12	23 56	0.048	144	60	0.054	171	63	0.059	202	68			
3000 1.91	0.048 13	34 56	0.053	159	60	0.058	183	63						
2500 2.29	0.053 14	48 56	0.058	174	60	0.060	189	63						
2000 2.86	0.058 10	62 56												
1800 3.18	0.060 10	67 56												
1600 3.58			<u> </u>											
1400 4.09														
1200 4.77 1000 5.73														
900 6.37														
800 7.16			i											
700 8.19														
600 9.55														
500 11.46														
450 12.73														
400 14.32											]			
350 16.37														
300 19.10	L		<u> </u>											
250 22.92														
200 28.65	L		J ]											
150 38.20 100 57.30														
75 76.39	L													
50 114.59														
	R(min) =	= 1660 ft	R(mi	n) = 20	)40 ft	R(mi	n) = 25	00 ft	R(mi	n) = 30	50 ft			

			W	YDC	)T S	relev	ation Tal	bles					
U	RE	BAI	N E	)E	SIC	GN	e(	max)	= 0.04 ft/ft				
		L	.ane	Adj	ustr	nent	t Fac	ctor L(adj	) = 1.0				
0.	ax)= 04 dj) =		e(max) f(max) GRAD	0.04 0.32 0.78		e(max) f(max) GRAD		L(adj) = 1.	Rev. 12-20-13				
1 12 ft I	.0 Lanes		V(R) V(D)	15 15		V(R) V(D)	20 20						
CU	RVE	15 n	1 <mark>ph</mark> (2	4km/h)	20 n	n <mark>ph</mark> (3	2km/h)	Definitions for	Superelevation Tables:				
R (ft)	D (deg)	e (ft/ft)	S (ft)	C (ft)	e (ft/ft)	S (ft)	C (ft)	R = Radius of Cur D = Degree of Cur	ve rve (100 ft arc length definition)				
23000	0.25	NC	0	0	NC	0	0	e = Superelevatio	n Rate				
20000	0.29	NC	0	0	NC	0	0		erelevation Runoff & Spiral Length				
17000	0.34	NC	0	0	NC	0	0		to full superelevation length.				
14000	0.41	NC	0	0	NC	0	0		ses 2/3 S off curve, 1/3 S on curve.				
12000	0.48	NC	0	0	NC	0	0	C = Length of Cro					
10000	0.57	NC	0	0	NC	0	0		crown) to flat crown length.				
8000	0.72	NC	0	0	NC	0	0		vn (typically 0.02 ft/ft)				
6000	0.95	NC	-	0	NC	-	-	RC = Reverse Cro	own (typically 0.02 ft/ft)				
5000 4000	1.15	NC NC	0	0	NC NC	0	0	L(adj) = Lane Adji	intmost Easter				
	1.43	NC	0	0	NC	0	0		just the length of S and C for				
3500 3000	1.04	NC	0	0	NC	0	0	multilane hi					
2500	2.29	NC	0	0	NC	0	0	indicidence in	giinayo.				
2000	2.86	NC	0	0	NC	0	0	L(adj) = 1.25	For 3 - lane roadways rotated				
1800	3.18	NC	0	0	NC	0	0	-()	about the centerline.				
1600	3.58	NC	0	0	NC	0	0						
1400	4.09	NC	0	0	NC	0	0	L(adj) = 1.5	For 4 - lane roadways rotated				
1200	4.77	NC	0	0	RC	32	32	-(,	about the centerline, and divided				
1000	5.73	NC	0	0	RC	32	32		4 - lane roadways rotated about				
900	6.37	NC	0	0	RC	32	32		the median edge of traveled way.				
800	7.16	NC	0	0	0.021	34	32						
700	8.19	RC	31	31	0.022	36	33	L(adj) = 1.75	For 5 - lane roadways rotated				
600	9.55	RC	31	31	0.023	37	32		about the centerline.				
500	11.46	RC	31	31	0.024	39	33						
450	12.73	0.021	32	30	0.025	41	33	Spiral transitions	should be considered when				
400	14.32	0.022	34	31	0.026	42	32	e, S, and C are	shaded.				
350	16.37	0.023	35	30	0.027	44	33						
300	19.10	0.024	37	31	0.028	45	32	Superelevation va	lues based on AASHTO 2011				
250	22.92	0.025	38	30	0.030	49	33	Greenbook.					
200	28.65	0.026	40	31	0.033	54	33						
150	38.20	0.028	43	31	0.036	58	32						
100	57.30	0.033	51	31	0.040	65	33						
75	76.39	0.036	55	31									
50	114.59	0.039	60	31	D/-	nin) = 0	06.8						
		K(n	nin) = 4	-2 π	K(r	nin) = 8	ποα						

WYDOT Superelevation Tables														
URBAN DESIGN e(max) = 0.04 ft/ft														
Lane Adjustment Factor L(adj) = 1.0														
e(max)= 0.04 L(adj) = 1.0 12 ft Lanes		e(max) 0.04 f(max) 0.23 GRAD 0.7 V(R) 24 V(D) 25			e(max) 0.04 f(max) 0.20 GRAD 0.66 V(R) 28 V(D) 30			e(max) 0.04 f(max) 0.18 GRAD 0.62 V(R) 32 V(D) 35			e(max) 0.04 f(max) 0.16 GRAD 0.58 V(R) 36 V(D) 40			
CURVE		25 mph (40km/h)			30 mph (48km/h)			35 mph (56km/h)			40 m		4km/h)	
R			e S C			e S C			e S C			e S C		
(ft)	(deg)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	
23000	0.25	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
20000	0.29	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
17000	0.34	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
14000	0.41	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
12000	0.48	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
10000	0.57	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
8000	0.72	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
6000	0.95	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
5000	1.15	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
4000	1.43	NC	0	0	NC	0	0	NC	0	0	RC	41	41	
3500	1.64	NC	0	0	NC	0	0	RC	39	39	RC	41	41	
3000	1.91	NC	0	0	NC	0	0	RC	39	39	0.021	43	41	
2500	2.29	NC	0	0	RC	36	36	RC	39	39	0.023	48	42	
2000	2.86	NC	0	0	RC	36	36	0.023	45	39	0.026	54	42	
1800	3.18	RC	34	34	0.021	38	36	0.024	46	38	0.027	56	41	
1600	3.58	RC	34	34	0.022	40	36	0.025	48	38	0.028	58	41	
1400	4.09	RC	34	34	0.023	42	37	0.026	50	38	0.030	62	41	
1200	4.77	0.021	36	34	0.024	44	37	0.028	54	39	0.032	66	41	
1000	5.73	0.023	39	34	0.026	47	36	0.030	58	39	0.034	70	41	
900	6.37	0.024	41	34	0.027	49	36	0.031	60	39	0.036	74	41	
800	7.16	0.024	41	34	0.028	51	36	0.033	64	39	0.037	77	42	
700	8.19	0.025	43	34	0.030	55	37	0.034	66	39	0.038	79	42	
600	9.55	0.027	46	34	0.032	58	36	0.036	70	39	0.040	83	42	
500	11.46	0.029	50	34	0.034	62	36	0.038	74	39				
450	12.73	0.030	51	34	0.035	64	37	0.039	75	38				
400	14.32	0.031	53	34	0.037	67	36	0.040	77	39				
350	16.37	0.032	55	34	0.038	69	36							
300	19.10	0.034	58	34	0.039	71	36							
250	22.92	0.036	62	34	0.040	73	37							
200	28.65	0.039	67	34										
150	38.20													
100	57.30													
75	76.39													
50	114.59													
R(min) = 154				54 ft	R(m	in) = 2	50 ft	R(min) = 371 ft R(min) =					33 ft	

WYDOT Superelevation Tables														
URBAN DESIGN e(max) = 0.04 ft/ft														
Lane Adjustment Factor L(adj) = 1.0														
e(max)=		e(max) 0.04		e(max) 0.04			e(max) 0.04			e(max) 0.04				
0.04		f(max) 0.15 GRAD 0.54		f(max) 0.14 GRAD 0.5			f(max) 0.13 GRAD 0.47			f(max) 0.12 GRAD 0.45				
	L(adj) = 1.0		GRAD V(R)	0.54 40		GRAD V(R)	0.5 44		GRAD V(R)	0.47 48		GRAD V(R)	0.45 52	
	Lanes		V(R) V(D)	45		V(R)	50		V(R)	55		V(R) V(D)	60	
	CURVE		45 mph (72km/h)			50 mph (80km/h)			55 mph (89km/h)			60 mph (97km/h)		
R	D	e	S	C	e S C			e S C			e S C			
(ft)	(deg)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	(ft/ft)	(ft)	(ft)	
23000	0.25	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
20000	0.29	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
17000	0.34	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
14000	0.41	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
12000	0.48	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
10000	0.57	NC	0	0	NC	0	0	NC	0	0	NC	0	0	
8000	0.72	NC	0	0	NC	0	0	RC	51	51	RC	53	53	
6000	0.95	NC	0	0	RC	48	48	RC	51	51	0.023	61	53	
5000	1.15	RC	44	44	RC	48	48	0.023	59	51	0.025	67	54	
4000	1.43	RC	44	44	0.023	55	48	0.026	66	51	0.028	75	54	
3500	1.64	0.022	49	45	0.025	60	48	0.027	69	51	0.030	80	53	
3000	1.91	0.024	53	44	0.027	65	48	0.030	77	51	0.033	88	53	
2500	2.29	0.026	58	45	0.029	70	48	0.032	82	51	0.035	93	53	
2000	2.86	0.029	64	44	0.032	77	48	0.035	89	51	0.038	101	53	
1800	3.18	0.030	67	45 44	0.033	79	48	0.037	94	51 51	0.039	104	53	
1600	3.58	0.032	71		0.035	84	48	0.038	97		0.040	107	54	
1400 1200	4.09	0.033	73	44 45	0.037	89 94	48 48	0.039	100	51 51				
1000	5.73	0.038	84	44	0.035	96	48	0.040	102	51				
900	6.37	0.030	87	44	0.040	30	40							
800	7.16	0.040	89	45										
700	8.19	0.010	00											
600	9.55													
500	11.46													
450	12.73													
400	14.32													
350	16.37													
300	19.10													
250	22.92													
200	28.65													
150	38.20													
100	57.30													
75	76.39													
50	114.59									00.0				
R(min) = 711 ft					R(m	in) = 9	26 ft	R(mi	n) = 11	190 ft	R(min) = 1500 ft			